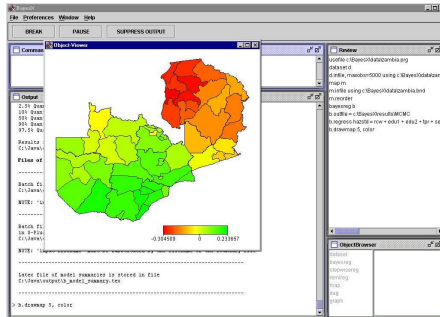




What is BayesX?



- The software BayesX provides powerful regression tools for analysing structured additive regression (STAR) and survival models. STAR models cover a number of well known model classes as special cases, e.g. generalised additive models, generalised additive mixed models, geoadditive models, dynamic models, varying coefficient models, and geographically weighted regression.

- BayesX supports both full Bayesian inference based on Markov chain Monte Carlo simulation techniques and empirical Bayes inference based on a mixed model representation of STAR models.

- In its current form, BayesX runs only under the various versions of the Windows operating system. A Linux version and an interface to R are work in progress.

- Contributions by Christiane Belitz, Eva-Maria Fronk, Andrea Hennerfeind, Manuela Hummel, Alexander Jerak, Petra Kragler and Leyre Osuna Echavarria.

Bayesian structured additive regression

- Structured additive regression extends and unifies several additive and geoadditive regression approaches.

- For exponential family models, a structured additive predictor is of the form

$$\eta_i = f_1(\nu_{i1}) + \dots + f_p(\nu_{ip}) + u_i^* \gamma_i,$$

where the ν_j are generic covariates of different type and dimension, and the f_j are (not necessarily smooth) functions of the covariates.

- Supported model terms include:

- Penalised splines and random walk priors for nonparametric effects $f(x)$ of continuous covariates x or time trends $f(t)$.
- Bivariate tensor product penalised splines for interaction surfaces $f(x, z)$.
- Varying coefficient terms with continuous and spatial effect modifiers.
- State space models for time-varying seasonal patterns $f(t)$.
- Random intercepts and random slopes.
- (Intrinsic) Markov random field priors for spatial effects $f_{spat}(s)$ based on regional data $s \in \{1, \dots, S\}$.
- Stationary Gaussian random field priors for spatial effects $f_{spat}(s)$ based on point-referenced data $s = (s_x, s_y)$.

- Supported univariate response distributions:

- Gaussian responses with identity link.
- Binary responses with logit, probit and complementary log-log link.
- Poisson responses with log-link.
- Gamma responses with log-link.
- Negative Binomial responses with log-link.

- Extensions for categorical regression models:

- Multinomial logit (and probit) models for unordered responses:

$$P(Y = r) = \frac{\exp(\eta^{(r)})}{1 + \sum_{s=1}^{K-1} \exp(\eta^{(s)})}.$$

$$\eta^{(r)} = u' \alpha^{(r)} + \bar{w}^{(r)'} \delta + \sum_{j=1}^l f_j^{(r)}(\nu_j) + \sum_{j=l+1}^p \bar{f}_j(\nu_j^{(r)}).$$

- Global covariates with category-specific effects.
- Category-specific covariates with global effects.
- Cumulative and sequential logit and probit models for ordered responses:

$$\eta^{(r)} = \theta^{(r)} - u' \alpha - w' \delta^{(r)} - \sum_{j=1}^l f_j(\nu_j) - \sum_{j=l+1}^p \bar{f}_j^{(r)}(\nu_j).$$

- Global effects and category-specific effects.
- In ordinal models, category-specific effects induce complicated constraints.

- Extensions for the analysis of survival times:

- Joint estimation of covariate effects and baseline hazard rate.
- Time-varying effects $g(t)x$ of covariates x .
- Inclusion of (piecewise constant) time-varying covariates.
- Left, right and interval censoring as well as left truncation.

Inference

- All effects can be subsumed in a unified framework.

- Each model term is associated with a vector of regression coefficients ξ_j with a multivariate Gaussian, partially improper prior

$$p(\xi_j | \tau_j^2) \propto \exp\left(-\frac{1}{2\tau_j^2} \xi_j' K_j \xi_j\right).$$

- The precision matrix K_j acts as a penalty matrix and the variance τ_j^2 represents the smoothing parameter.

- Inference can be performed either fully Bayesian based on MCMC or empirically Bayesian based on a mixed model representation.

- Key features of fully Bayesian inference:

- Additional inverse Gamma priors are assigned to the variance parameters τ_j^2 .
- The precision matrix K_j is usually sparse. Sparse matrix computations can be used for the construction of efficient updating schemes.
- Update parameters of one term in a block based on iteratively weighted least squares proposals derived from generalised additive model backfitting equations.
- Data augmentation in models with underlying latent Gaussian variables allows for Gibbs sampling in binary and categorical probit models.

- Key features of empirical Bayes inference:

- Consider variance parameters as unknown constants and estimate them based on their marginal posterior.
- Mixed model methodology can be used to do this: Split the partially improper prior for ξ_j in two parts with proper and improper prior density. The resulting model can be interpreted as a mixed model.
- Marginal likelihood / Restricted maximum likelihood estimates for the variances can be derived from standard mixed model algorithms. This usually involves a Laplace approximation to the marginal posterior.

Example: Leukemia survival data

- Survival time of adults after diagnosis of acute myeloid leukemia.

- 1,043 cases diagnosed between 1982 and 1998 in Northwest England.

- 16 % (right) censored.

- Continuous and categorical covariates:

age age at diagnosis,
wbc white blood cell count at diagnosis,
sex sex of the patient,
tpi Townsend deprivation index.

- Spatial information in different resolution.

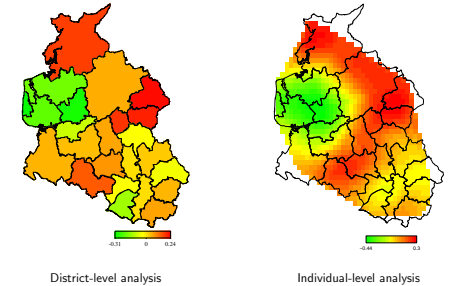
- Suitable model for the hazard rate:

$$\lambda(t; \cdot) = \exp[f_0(t) + f_1(\text{age}) + f_2(\text{wbc}) + f_3(\text{tpi}) + f_{spat}(s_i) + \gamma_1 \text{sex}]$$

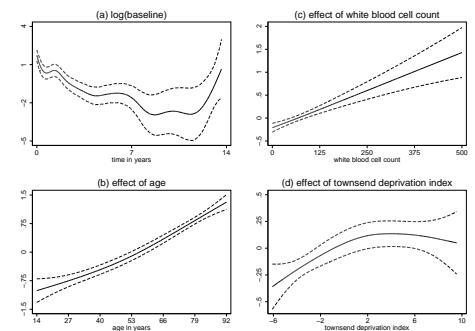
where

- $f_0(t) = \log(\lambda_0(t))$ is the log-baseline-hazard,
- f_1, f_2, f_3 are nonparametric functions of age, white blood cell count and deprivation, and
- f_{spat} is a spatial function.

- Results for the spatial effect:



- Results for the nonparametric effects:



Further information

- Download and further information:

<http://www.stat.uni-muenchen.de/bayesx>

- Contact:

bayesx@stat.uni-muenchen.de

- Selected references:

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